

HW 1

Analog Filters.

E4915

Prepared by

Vincent
Samsheer

Prob 1.

Fig 1(a)

$$H(s) = \frac{V_o(s)}{V_i(s)} = \frac{-Z_2}{Z_1} \quad \begin{aligned} Z_2 &= R \parallel \frac{1}{sC} \\ Z_1 &= R \end{aligned}$$
$$= \frac{-1}{1+sRC}$$

$$h(t) = \mathcal{L}^{-1} H(s) = \frac{-1}{RC} e^{-t/RC}$$

$$\left[\mathcal{L}^{-1} \frac{1}{s+a} = e^{-at} \right]$$

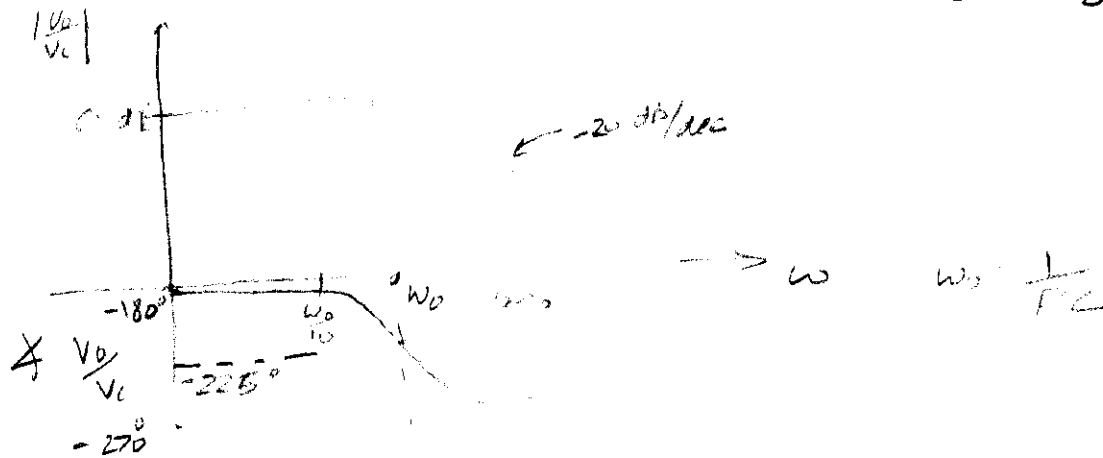


Fig 1(b)

$$H(s) = \frac{V_o(s)}{V_i(s)} = \frac{-Z_2}{Z_1} \quad \begin{aligned} Z_2 &= 2R \parallel \frac{1}{sC} \\ Z_1 &= 2R \end{aligned}$$
$$= \frac{-1}{1+sRC}$$

$H(s)$ is same for both det's. $\therefore h(t) = \frac{-1}{RC} e^{-t/RC}$
No diff. b/w the det's as far as Transfer function & impulse response are concerned

Probs 2

Fig 1(a)

$$i_o(t) = -i_L(t)$$

$$= -\frac{v_L(t)}{R}$$

$$= -\frac{1}{R} \cos(t/RC) \text{ A}$$

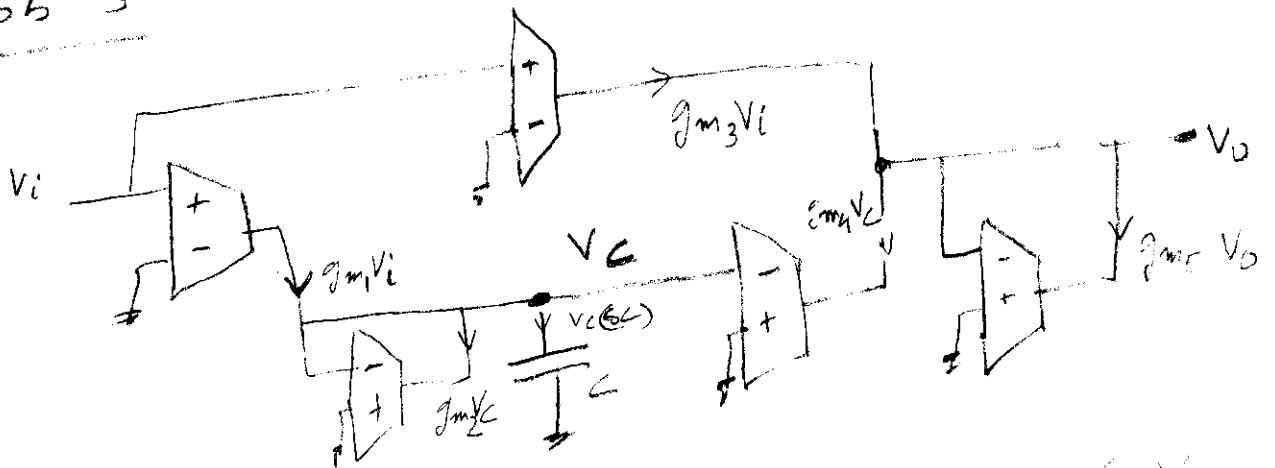
Fig 1(b)

$$i_o(t) = -\frac{v_L(t)}{2R}$$

$$= -\frac{1}{2R} \cos t/RC$$

The magnitude of input impedance for second ckt is double that of the first circuit

Prob 3



Apply Kirchhoff's current law at V_c & V_o

At V_c

$$g_{m1}V_i = g_{m2}V_c + V_c(sC)$$

$$V_c = \frac{g_{m1}V_i}{g_{m2} + sC}$$

At V_o

$$g_{m3}V_i = g_{m4}V_c + g_{m5}V_o$$

Eliminating V_c

$$g_{m3} - \frac{g_{m1}g_{m4}}{g_{m2} + sC} = g_{m5}V_o$$

$$\frac{V_o}{V_i} = \frac{g_{m3}(g_{m2} + sC) - g_{m1}g_{m4}}{g_{m5}(g_{m2} + sC)}$$

$$= \frac{g_{m3}g_{m2}g_{m1}g_{m4}}{g_{m5}g_{m2}} \left(\frac{1 + \frac{sC}{g_{m2}} - \frac{g_{m1}g_{m4}}{g_{m2}}}{1 + \frac{sC}{g_{m2}}} \right)$$

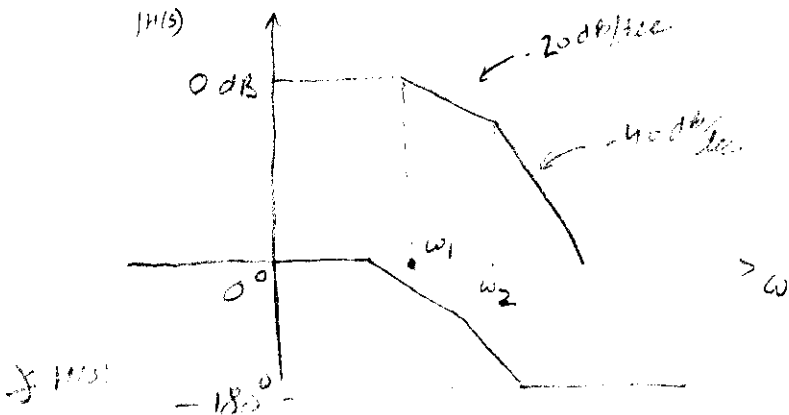
P4

Fig 3(a)

Identifying the cascade of 2 inverting amplifiers.

$$H(s) = \frac{V_o}{V_i} = \frac{V_x}{V_i} \cdot \frac{V_o}{V_x} = \frac{1}{(1 + sR_1C_1)(1 + sR_2C_2)}$$

(Refer Prob 1A)



$$\omega_1 = \frac{1}{R_1C_1}$$

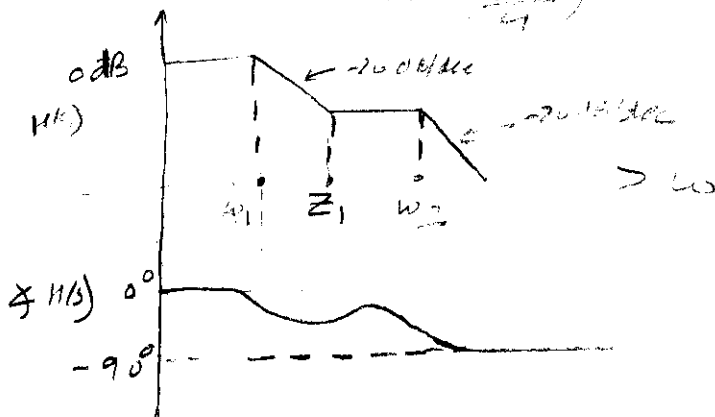
$$\omega_2 = \frac{1}{R_2C_2}$$

Fig 3(b)

$$H(s) = \frac{V_o}{V_i} = \frac{V_x}{V_i} \cdot \frac{V_o}{V_x}$$

$$\frac{V_o(s)}{V_x(s)} = \frac{R_2}{1 + sR_2C_2} = \frac{1 + sR_2C_2}{1 + sR_2C_2} \cdot \frac{R_2}{1 + sR_2C_2}$$

$$H(s) = \frac{V_o(s)}{V_i(s)} = \frac{1 + sR_2C_2}{1 + sR_2C_2} \cdot \frac{1}{1 + sR_1C_1}$$



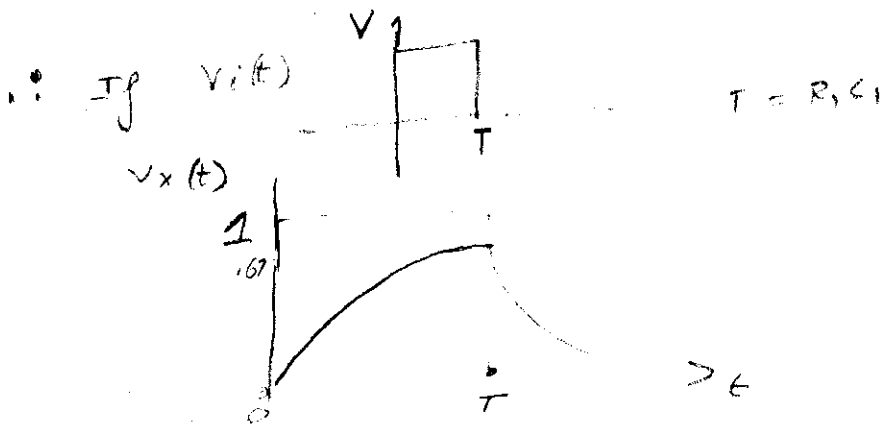
$$\omega_1 = \frac{1}{R_1C_1}$$

$$\omega_2 = \frac{1}{R_2C_2}$$

Prob 5

$$\frac{V_x(s)}{V_i(s)} = \frac{1}{1 + sRC_1}$$

Then we know Low pass filter characteristics

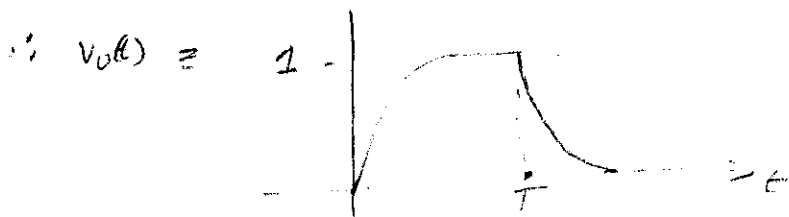


Time constant of exponential increase & decay will be $\tau = RC_1$

$$\frac{V_o(s)}{V_i(s)} = \frac{1 + sR_2C_2}{1 + s\left(\frac{R_1C_1}{2}\right)} \quad \forall \frac{1}{1 + sRC_1}$$

$$= \frac{1}{1 + s\left(\frac{R_1C_1}{2}\right)} \quad \forall R_1C_1 = R_2C_2$$

Time constant of filter $= \frac{R_1C_1}{2} < T$



Refer Appendix F for more details.

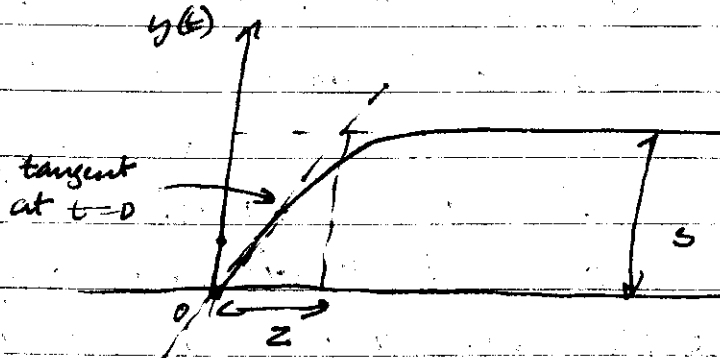
Prob 5

$$\frac{V_x(s)}{V_i(s)} = \frac{1}{1+sRC}$$

These are lowpass filter characteristics.

In response to a step signal of height S , a low pass STA produces a waveform as shown below

$$y(t) = y_{\infty} - (y_{\infty} - y_{0+}) e^{-t/\tau} \quad \tau = RC$$



where $y_{\infty} \equiv$ final value or value at $t = \infty$
 $y_{0+} \equiv$ value immediately after $t = 0^+$

In our case $y_{\infty} = S$ and $y_{0+} = 0$

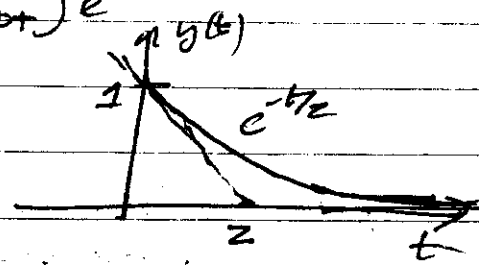
$$\therefore y(t) = S(1 - e^{-t/\tau})$$

Similarly in response to a falling step (or a -ve step)

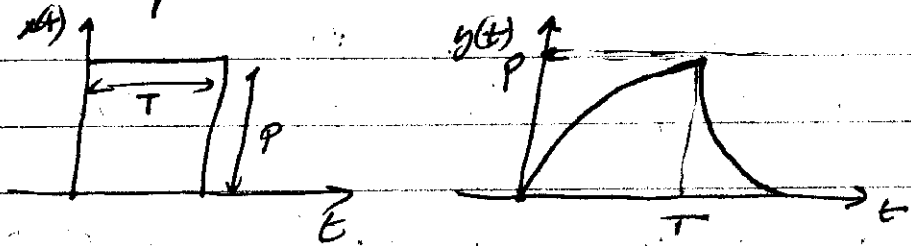
$$y(t) = y_{\infty} - (y_{\infty} - y_{0+}) e^{-t/\tau}$$

$y_{\infty} = 0$ $y_{0+} = 1$

$$\therefore y(t) = e^{-t/\tau}$$

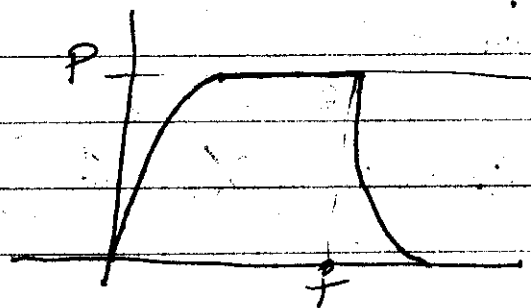


∴ A low pass STL ans response to a pulse will be as shown below

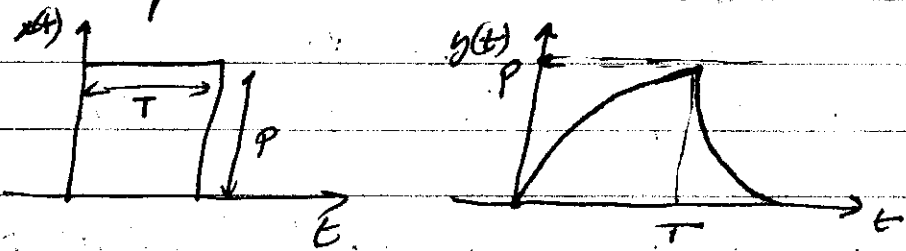


The L.P. circuit does not respond to the step change at the leading edge of the pulse, rather the output starts to rise exponentially towards final value of P . The exponential rise is however stopped at time $t=T$, at the trailing edge of the pulse. The output will then respond by starting an exponential decay toward final value of the input which is zero.

In well designed system, in which pulses are to be transmitted (ex. digital systems) distortion due to low pass effects is kept low by arranging Z to be much smaller than width T . In this case response is as shown.



∴ A low pass STC circuit response to a pulse will be as shown below



The L.P. circuit does not respond to the step change at the leading edge of the pulse, rather the output starts to rise exponentially towards final value of P . The exponential rise is however stopped at time $t=T$, at the trailing edge of the pulse. The output will then respond by starting an exponential decay toward final value of the input which is zero.

In well designed system, in which pulses are to be transmitted (ex. digital systems) distortion due to low pass effects is kept low by arranging Z to be much smaller than width T . In this case response is as shown.

